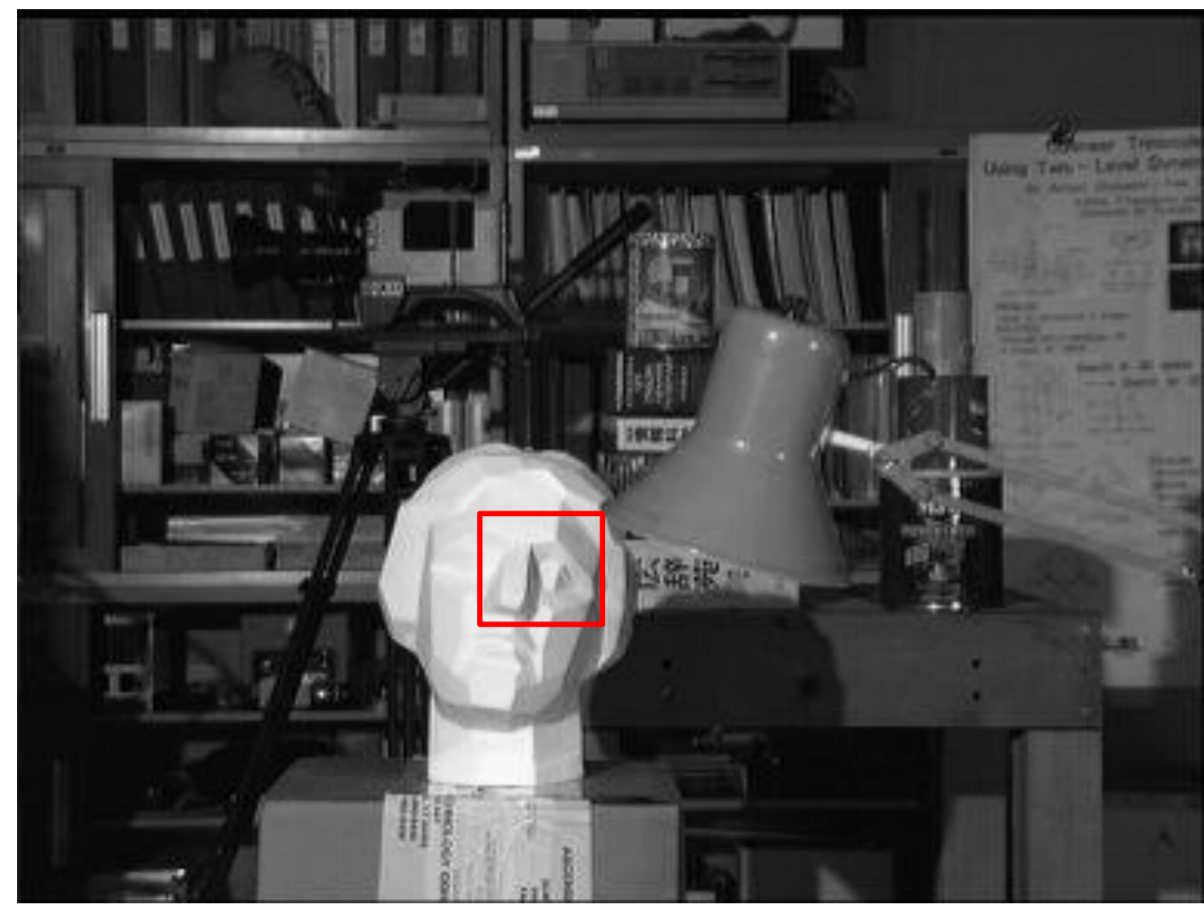
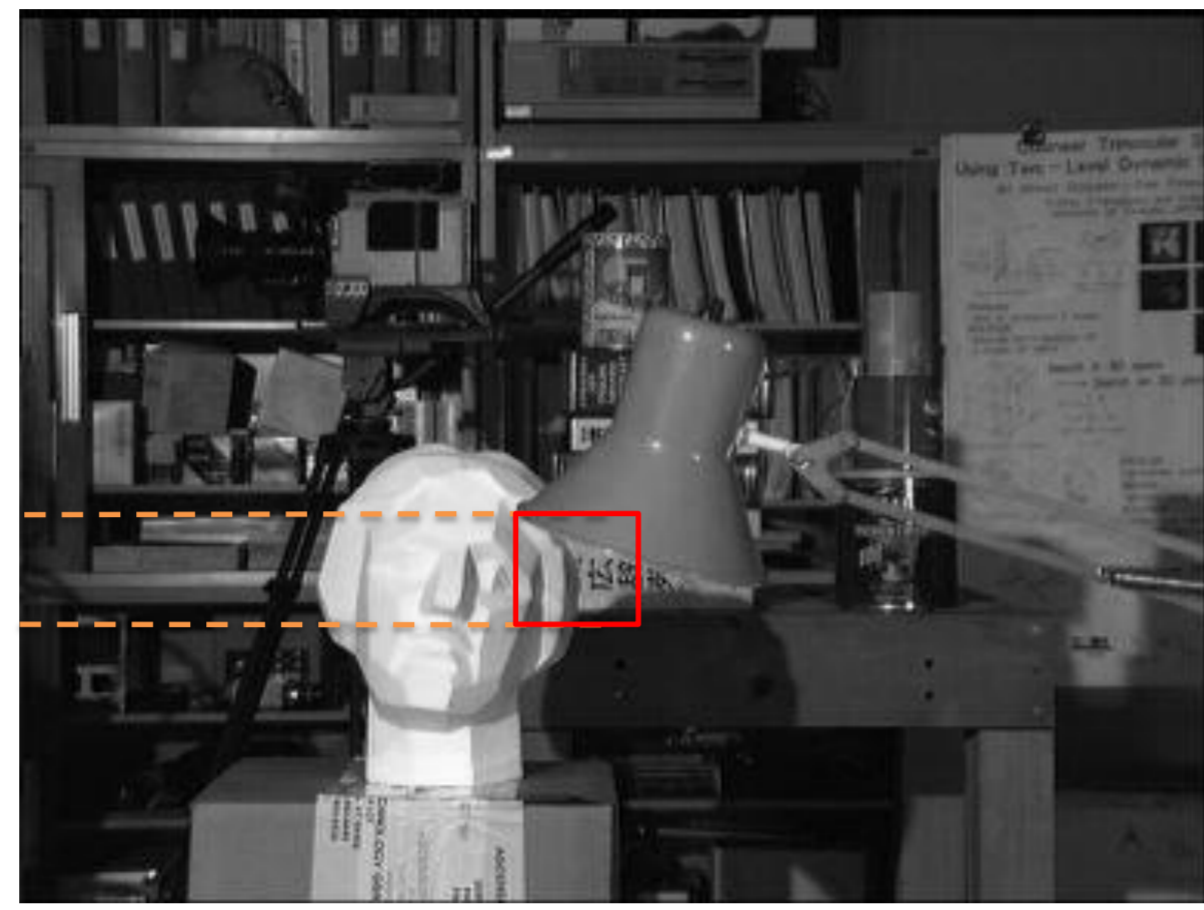


### 1. What is stereo matching?

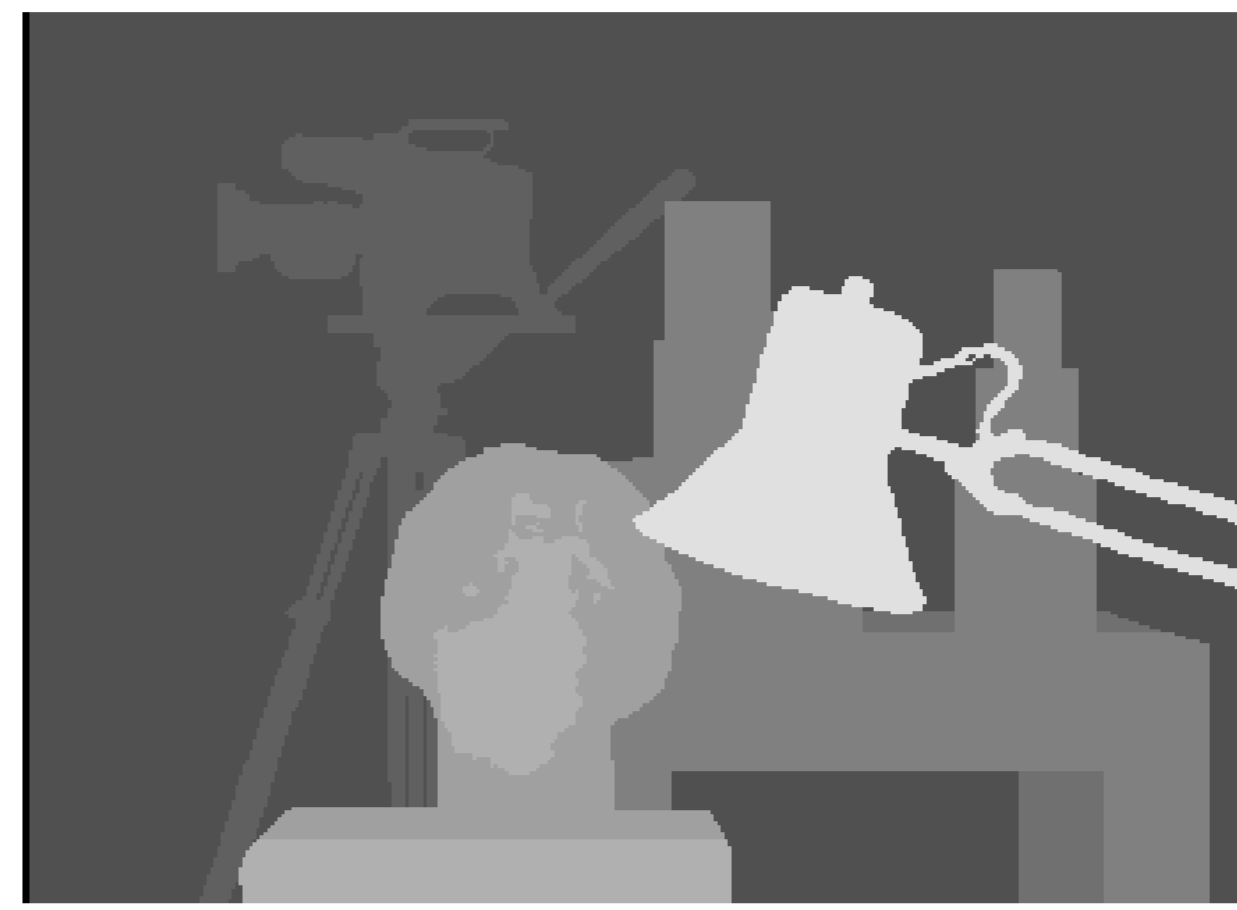
For a point in image 1, where is the corresponding point in image 2?



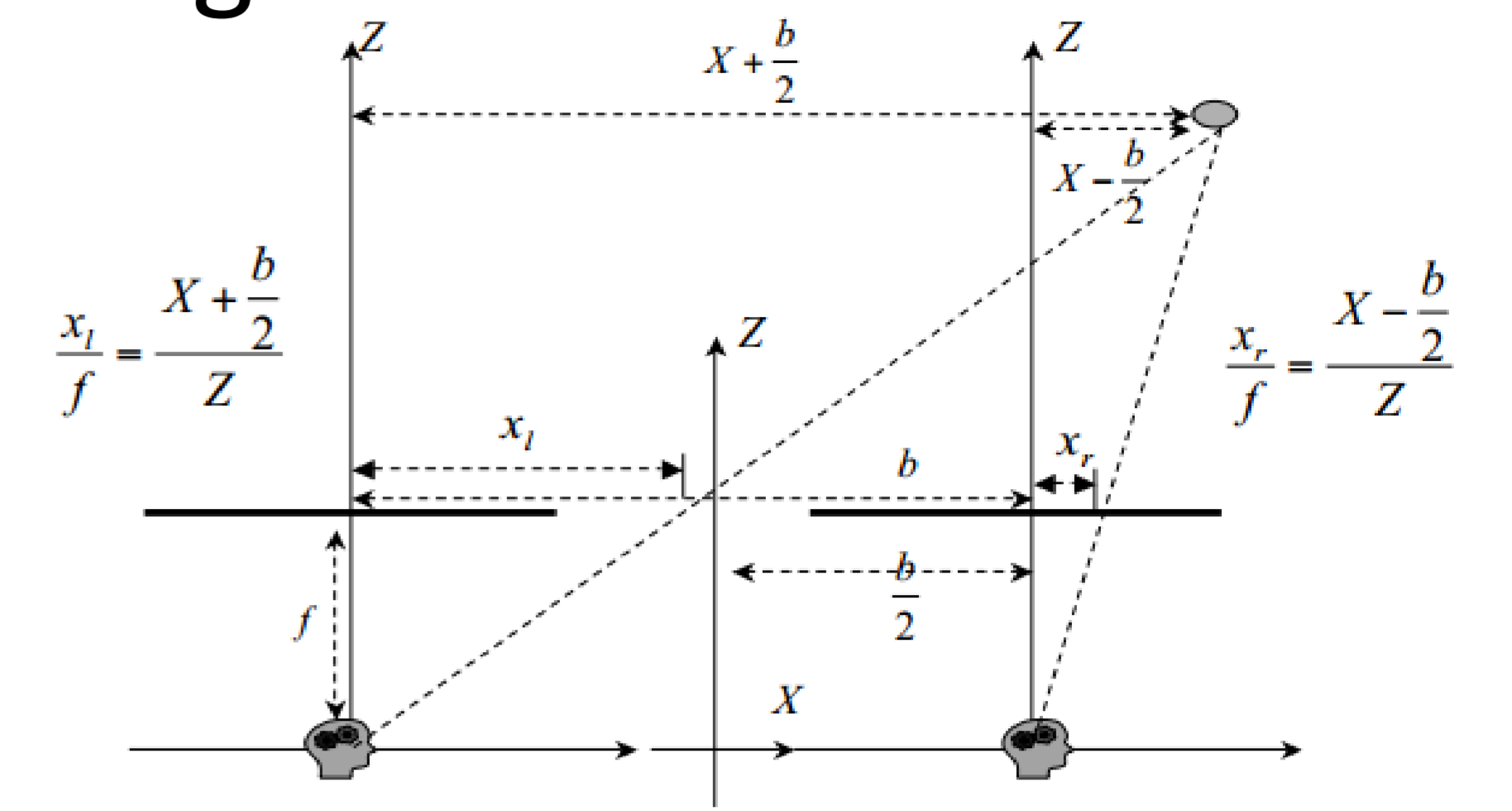
Left image



Right image



Disparity map



Disparity and depth

$$\frac{x_l - x_r}{f} = \frac{b}{Z}$$

### 2. Local stereo matching algorithm

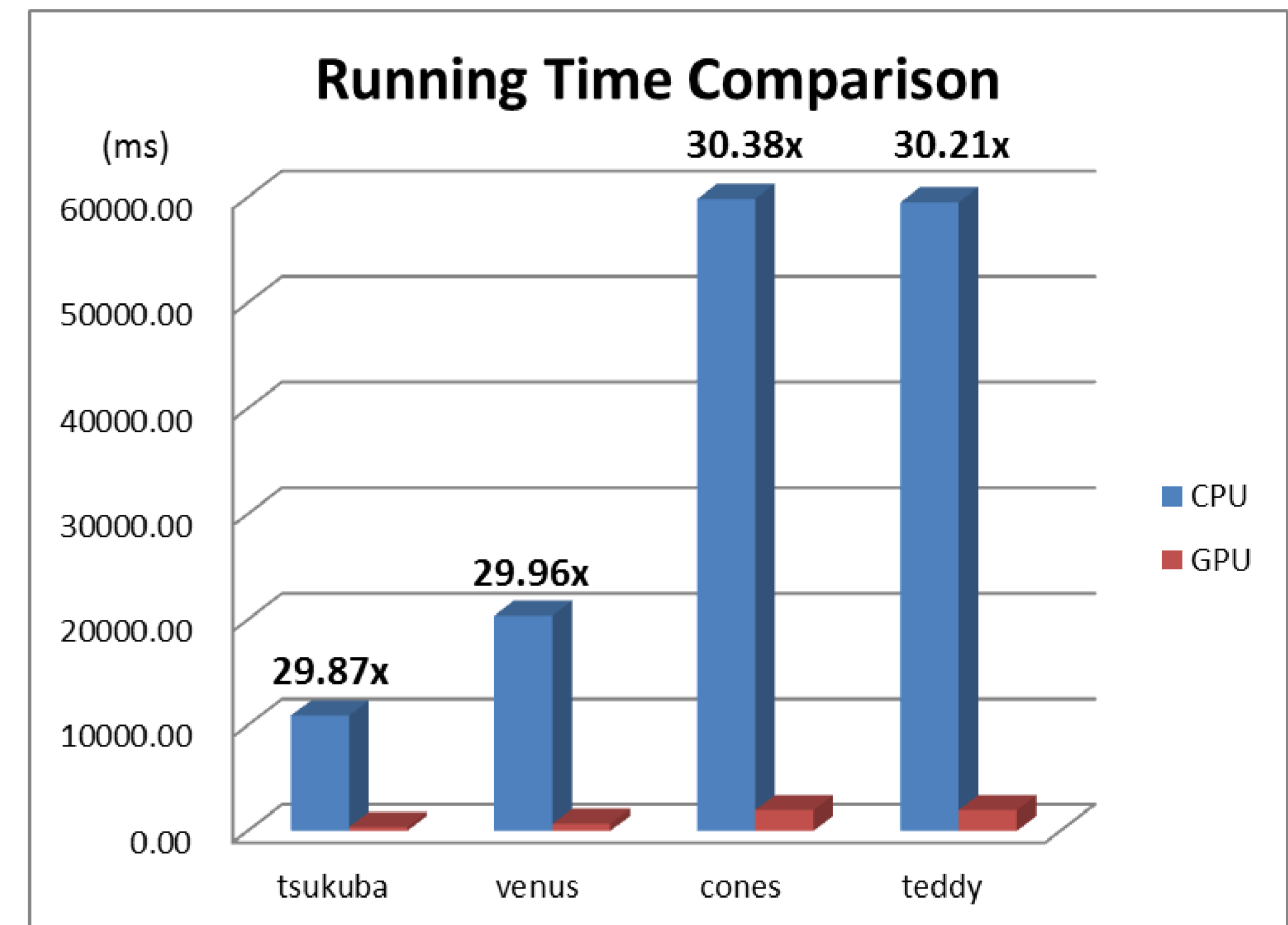
2.1 Adaptive support weight method:

$$w(p, q) = \exp\left(-\left(\frac{\Delta c_{pq}}{\gamma_c} + \frac{\Delta g_{pq}}{\gamma_p}\right)\right) \quad E(p, \bar{p}_d) = \frac{\sum_{q \in N_p, \bar{q}_d \in N_{\bar{p}_d}} w(p, q)w(\bar{p}_d, \bar{q}_d)e(q, \bar{q}_d)}{\sum_{q \in N_p, \bar{q}_d \in N_{\bar{p}_d}} w(p, q)w(\bar{p}_d, \bar{q}_d)}$$

Data set	Size	Disparities	Operation	CPU time(ms)	GPU time(ms)	Speedup ratio
tsukuba	354x288	15	Color conversion	72.51	3.67	<b>19.74</b>
			Stereo Matching	10856.90	362.21	<b>29.97</b>
			<b>Total</b>	<b>10929.41</b>	<b>365.89</b>	<b>29.87</b>
venus	434x383	19	Color conversion	102.45	4.35	<b>23.57</b>
			Stereo Matching	20288.20	676.34	<b>30.00</b>
			<b>Total</b>	<b>20390.65</b>	<b>680.68</b>	<b>29.96</b>
cones	450x375	59	Color conversion	110.46	4.36	<b>25.32</b>
			Stereo Matching	59761.80	1966.17	<b>30.40</b>
			<b>Total</b>	<b>59872.26</b>	<b>1970.53</b>	<b>30.38</b>
teddy	450x375	59	Color conversion	100.34	4.38	<b>22.90</b>
			Stereo Matching	59436.90	1966.65	<b>30.22</b>
			<b>Total</b>	<b>59537.24</b>	<b>1971.03</b>	<b>30.21</b>

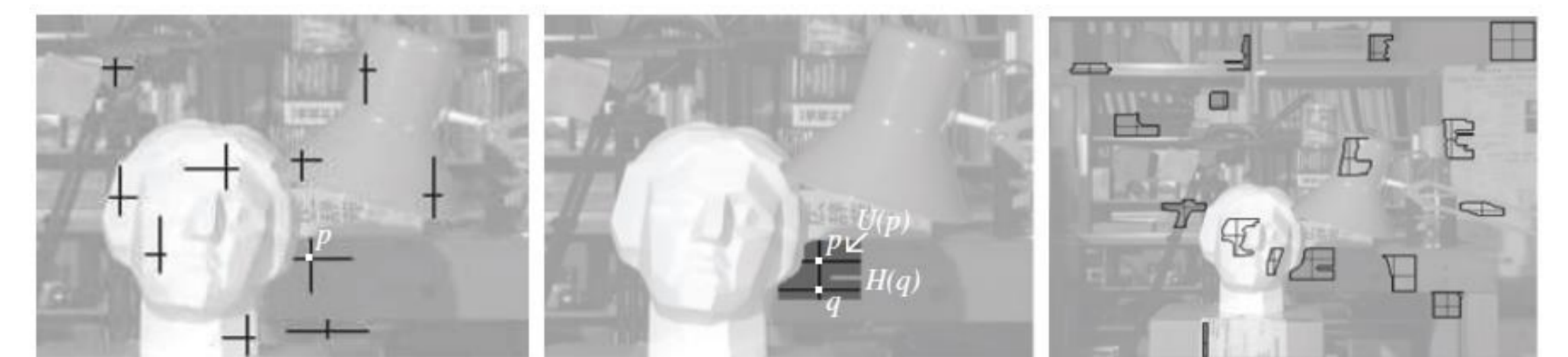
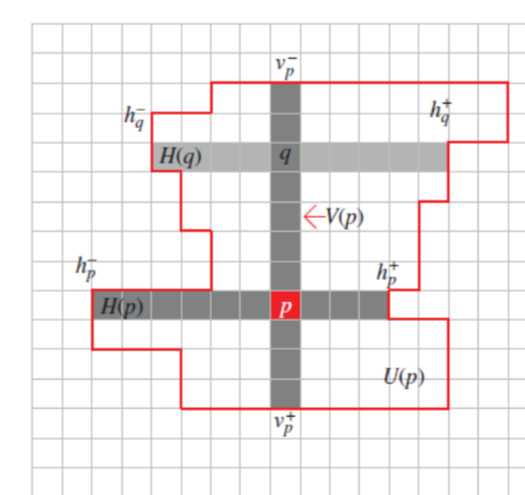
CPU: Intel CORE i7 2630QM

GPU: NVIDIA GT 540M

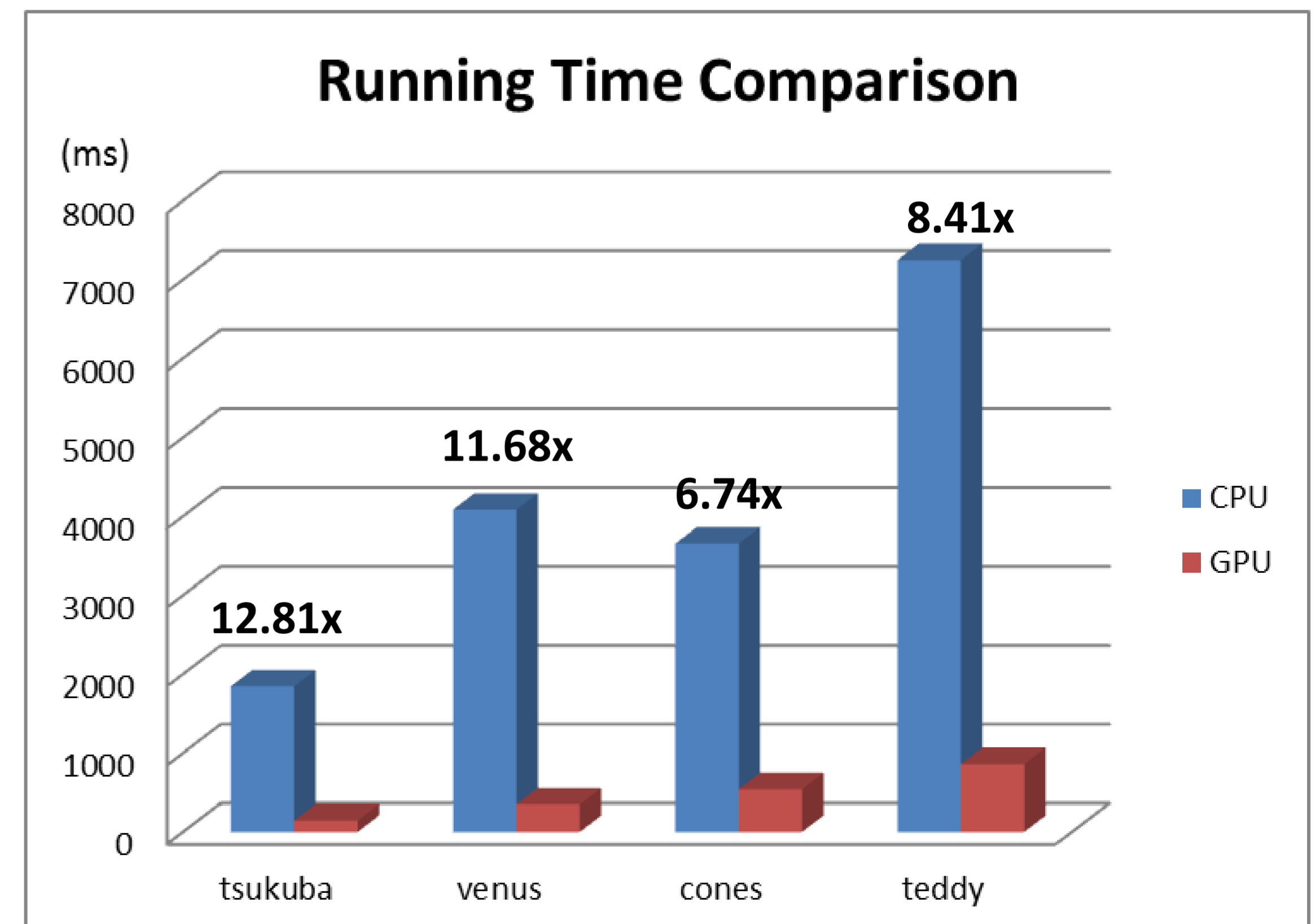


2.2 Cross-based method:

$$\bar{E}_d(p) = \frac{1}{\|U_d(p)\|} E_d(p) = \frac{1}{\|U_d(p)\|} \sum_{s \in U_d(p)} e_d(s)$$



Data set	Size	Disparities	Operation	CPU time(ms)	GPU time(ms)	Speedup ratio
tsukuba	354x288	15	Cross Construction	55.90724	3.864253	<b>14.4678</b>
			Stereo Matching	1699.217	126.2564	<b>13.45846</b>
			Refinement	88.5829	13.73011	<b>6.451727</b>
			<b>Total</b>	<b>1843.707</b>	<b>143.8507</b>	<b>12.81681</b>
venus	434x383	19	Cross Construction	90.45587	6.000697	<b>15.07423</b>
			Stereo Matching	3840.325	316.73	<b>12.12492</b>
			Refinement	153.7537	26.78129	<b>5.741086</b>
			<b>Total</b>	<b>4084.535</b>	<b>349.512</b>	<b>11.68639</b>
cones	450x375	59	Cross Construction	61.5833	5.406342	<b>11.39094</b>
			Stereo Matching	3511.401	510.8408	<b>6.873768</b>
			Refinement	80.91072	25.18789	<b>3.212287</b>
			<b>Total</b>	<b>3653.895</b>	<b>541.435</b>	<b>6.748538</b>
teddy	450x375	59	Cross Construction	75.64388	5.934521	<b>12.74642</b>
			Stereo Matching	7041.813	822.6964	<b>8.55943</b>
			Refinement	129.2049	32.60316	<b>3.962956</b>
			<b>Total</b>	<b>7246.661</b>	<b>861.2341</b>	<b>8.414276</b>



### 3. Performance optimization

- Sometimes it's better to recompute than to cache
- Coalescing memory operations
- Optimize work group size

